KAAN BEYDUZ

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EDUCATION & QUALIFICATIONS

University of California, Berkeley (UC, Berkeley)

Master of Engineering in Mechanical Engineering: Control of Robotic and Autonomous Systems with Engineering Data Science TECH+PLUS Certification

August 2023 - May 2024

GPA: 3.87 / 4.00

Relevant Coursework:

- MECENG 236: Control and Dynamics of Unmanned Aerial Vehicles
- MECENG 232 233: Advanced Controls I and II (Modern Control Theory)
- MECENG 231B: Experiential Advanced Controls II (Prediction and Estimation)
- MECENG 235: Design of Microprocessor-Based Mechanical Systems (LabVIEW course)
- MECENG 249: Machine Learning Tools for Modeling Energy Transport and Conversion Processes

University of Wisconsin-Madison (UW-Madison)

Bachelor of Science in Mechanical Engineering with Manufacturing Engineering Certification

Sept. 2019 - May 2023

GPA: 3.69 / 4.00

Relevant Coursework:

- ME368: Engineering Measurement and Instrumentation (LabVIEW course)
- ME 447: Computer Control of Machines and Processes
- **ME 439**: Introduction to Robotics

SKILLS & ABILITIES

Programming Languages:

- **Phyton** (SciPy, FiPy, Ultralytics)
- MATLAB & Simulink (control design, image/signal processing)
- C++ (Arduino/ESP32 hardware implementations)
- LabVIEW (GUI design)
- **ROS** (Noetic, Foxy for ROS2)
- RAPID (ABB Robot Programming Language)

Technical Skills:

- Control algorithm development for guidance and navigation
- Machine Learning for mechanical design and modeling
- Data analysis for forecasting, sparsity and filtering
- Mechatronics system modeling and software development
- Image processing and analysis

Interpersonal Skills:

- Highly adaptive in different work environments
- Enthusiastic for new challenges
- Effective communicator across technical teams
- Quick learner and resilient under pressure
- Proficient in Agile development practices

WORK EXPERIENCE

Fluffy Network Attached Storage (Fluffy NAS): Home Storage Devices Co-Founder

Rockville, Maryland, USA June 2024 - present

- Crowd-funded the Fipsy FPGA V2 educational development board, spearheading marketing strategies.
- Collaborated with manufacturers to asses cost and production quantities for the beta product launch of Fluffy NAS PCB board. Directed the mechanical design and oversaw manufacturing of the Fluffy NAS Lite PCB board.
- **Simulated and evaluated active and passive cooling methods** for the Fluffy NAS Lite PCB board, optimizing the casing design to enhance thermal performance.

Ozler Plastic Corp. (Multi-national Injection Molding Company)

Robotics and Automation Engineer Intern (1 month)

Avcilar, Istanbul, Turkey January 2023

- **Developed PLC ladder logic** of the packaging process using Automation Studio and designed tool paths for a 6 degrees of freedom ABB brand robot, using Robot Studio.
- **Simulated and animated the equipment layout** and workflow for the packaging process, delivering a comprehensive presentation to management.
- Programmed and validated robotic tool paths using RAPID language, conducting hands-on testing on decommissioned ABB robot with the ABB Teach Pendant.

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Yucel Industrial Pipes and Profiles LLC., (Yucel Boru)

Maintenance Engineer Intern

Gebze, Kocaeli, Turkey June 2022 - July 2022

- **Diagnosed machine component malfunctions** and collaborated with the chief mechanical engineer to oversee bimonthly maintenance, ensuring operational reliability.
- Authored comprehensive technical documentation on roll-forming and slitting machines, solid-state high-frequency welding, electric generators, conveyors, hydraulic and pneumatic control systems.
- Integrated sensors and contributed to PLC logic design into a factory's process line, enabling performance monitoring and optimized machine operations.

Uskudar American Academy (UAA)

Part Time Teacher and Team Mentor

Online

Sept. 2020 - August 2021

- **Directed the development** of an underwater drone tailored for marine research applications, modeling propellers, chassis and control laws using MATLAB/Simulink and Solidworks.
- **Automated** an air-filtering "Covid-Bot" for classroom interaction and effective air filtration. Validated navigation algorithms in ROS and guided the engineering and manufacturing process.

ACCOMPLISHMENTS & SCIENTIFIC RESEARCH

Pfizer Drone Racing League Artificial Intelligence Flight Competition Grand Prize Winner

Nov. 2024

- Engineered a solution to an object tracking problem, and earned a racing drone and merch worth \$5,000.
- **Integrated** the YOLOv8 object detection algorithm with Extended Kalman Filter and Optical Flow methods to extract precise 2D position data from video footage of a drone operating in an indoor environment.

Master's CAPSTONE Design Project at UC, Berkeley HIPER Lab: Design and Control of a Multimodal Flying - Driving Delivery Robot

Advisor: Dr. Mark Mueller

Sept. 2023 – May 2024

- **Developed Python and ROS based software** for the navigation, control and state estimation of a hybrid delivery robot, integrating flying and driving modes with precise position control.
- **Modeled the transmission system dynamics** using MATLAB/Simulink, optimizing design parameters for seamless hybrid mode transitions. 3D modeled the transmission components in Solidworks, supervised the manufacturing process, and validated performance against MATLAB simulations.
- Lead a multidisciplinary team through the engineering process, coordinating team meetings, managing timelines, and ensuring successful project submission.

UW-Madison Undergraduate Independent Research: Laboratory Measurement of the Effect of Surface Waves on the Settling Velocity of Microplastics

Advisor: Dr. Nimish Pujara

October 2021 - May 2023

- Awarded the Hilldale Undergraduate Research Fellowship for a proposed study on microplastic particle interactions with surface waves, securing \$3,000 in personal funding and \$,1000 for research expenses.
- **Presented research findings** at the Wisconsin American Water Research Association (AWRA) 2022 Annual Meeting as a poster speaker and at the University of Wisconsin Research Symposium in April 2023.
- Engineered an innovative particle-dropping mechanism with Arduino-controlled timing for precision particle imaging, and processed Particle Image Velocimetry (PIV) data using MATLAB image processing toolbox.

Bachelor's CAPSTONE Project at UW-Madison: Calibration Techniques for an Inertial Measurement Unit *Advisor: Dr. Michael Cheadle*February 2022 - Dec. 2022

- **Developed an image processing algorithm** in MATLAB to accurately measure the motion of the calibration device and a MATLAB application to visualize results, and provide real-time feedback to optimize device parameters.
- Constructed a user interface with low-voltage electronics, including knobs and buttons, and utilized Arduino for motion feedback and control. Integrated safety mechanisms to ensure seamless high-to-low voltage conversions.